

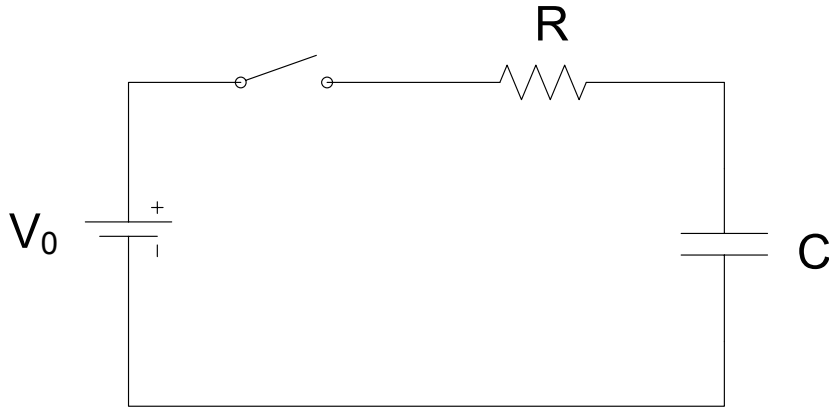
# **Physics 6C**

## **Introduction to Physics III**

### **Electricity and Magnetism**

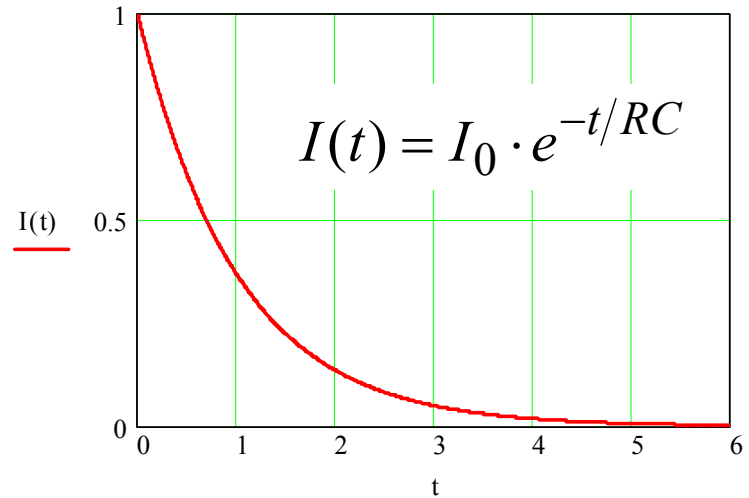
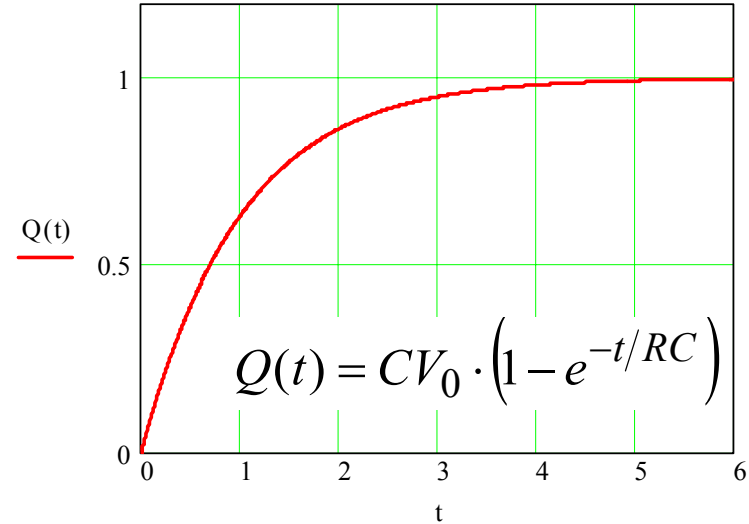
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# RC Circuit: Charging



This is an example of a “transient” response. The current changes with time after the switch closes and eventually reaches a constant value of zero.

For AC circuits, we are not interested in the transient response, but instead we consider *only the behavior after the circuit has been on for a long time*.



# RC Circuit with AC Source

Kirchhoff's loop rule holds at every instant in time:

$$\mathcal{E}(t) = v_R(t) + v_C(t)$$

We want to find the resulting current, *which generally will not be in phase with the voltage*:

$$i(t) = I_{\max} \cos(\omega t + \phi)$$

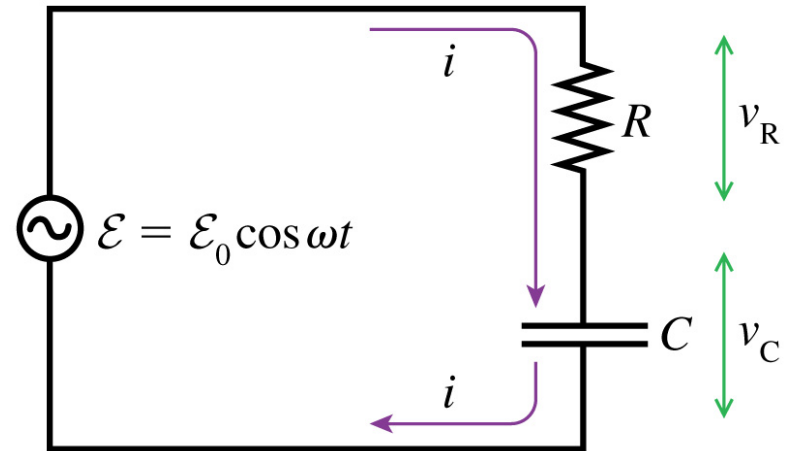
We have to find both the amplitude  $I_{\max}$  and the phase  $\phi$ .

$$v_R = I_{\max} R \cos(\omega t + \phi)$$

The resistor voltage is in phase with current

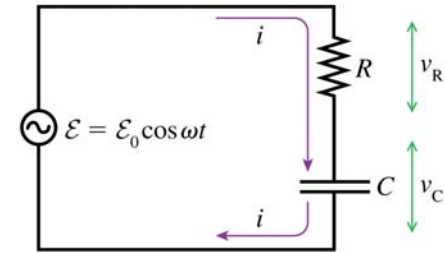
$$v_C = I_{\max} \frac{1}{\omega C} \cos\left(\omega t + \phi - \frac{\pi}{2}\right)$$

The capacitor voltage lags behind the current by 90 degrees.



*Assume that the source has been turned on for a long time, so all transients have died out.*

# RC Circuit



$$\mathcal{E}(t) = v_R(t) + v_C(t)$$

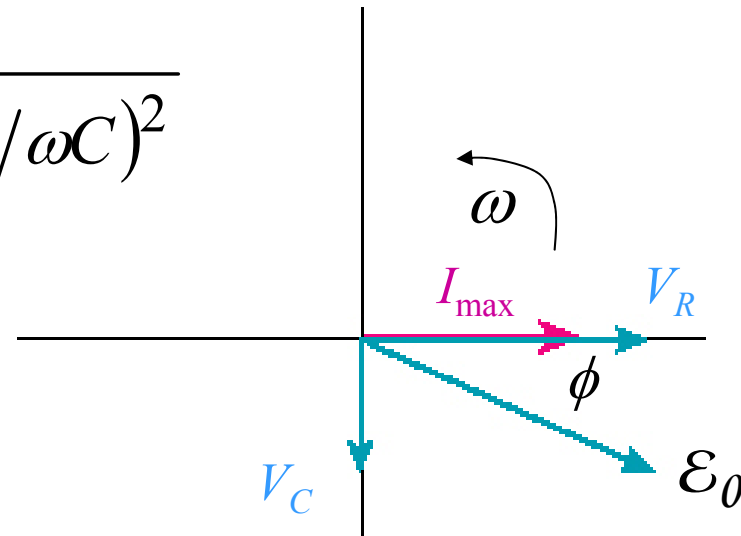
$$\mathcal{E}_0 \cos \omega t = I_{\max} R \cos(\omega t + \phi) + I_{\max} \frac{1}{\omega C} \cos\left(\omega t + \phi - \frac{\pi}{2}\right)$$

This equation can be solved for both  $I_{\max}$  and  $\phi$  by using trig identities, but it is easier to do it graphically using phasors. The algebra then just looks like vector addition.

$$\mathcal{E}_0 = \sqrt{V_R^2 + V_C^2} = I_{\max} \sqrt{R^2 + (1/\omega C)^2}$$

$$\tan \phi = \frac{V_C}{V_R} = \frac{1}{\omega RC}$$

As in a circuit with just a capacitor, the voltage lags behind the current, but by less than 90 degrees.  $\phi > 0$



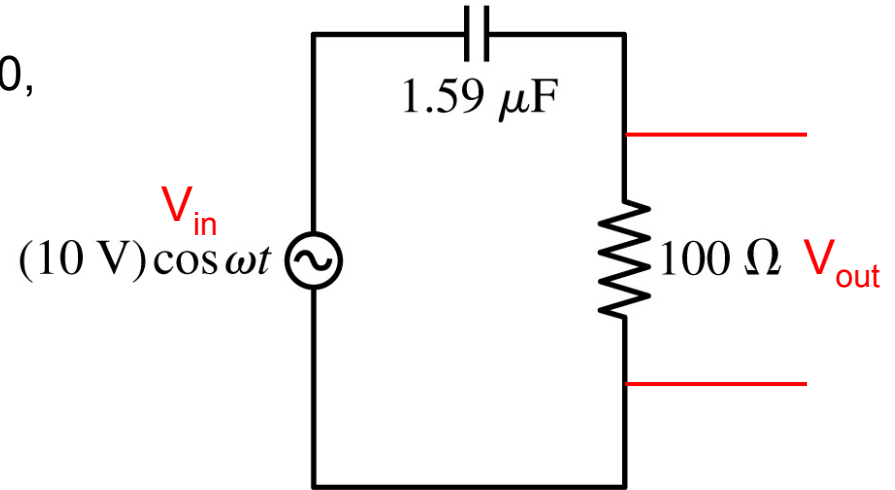
$$\text{Note: } Z = \sqrt{R^2 + X_C^2}$$

# Problem 35-36

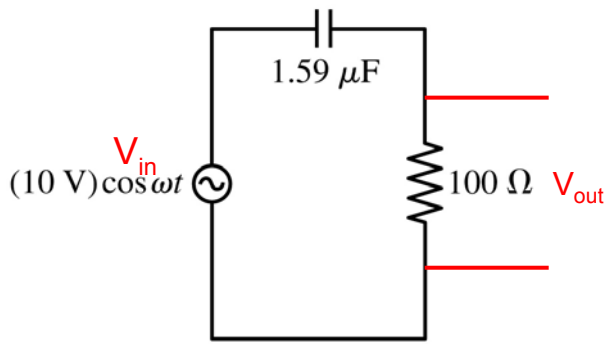
- Evaluate  $V_R$  at emf frequencies 100, 300, 1000, 3000, and 10,000 Hz
- Graph  $V_R$  vs frequency.

This is an example of a “high pass filter.”

Note that for  $f=0$  (DC) the current must be zero, and therefore  $V_{out}$  is 0.



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# Problem 35-36

$$R := 100 \quad V_{in} := 10 \quad C := 1.59 \cdot 10^{-6}$$

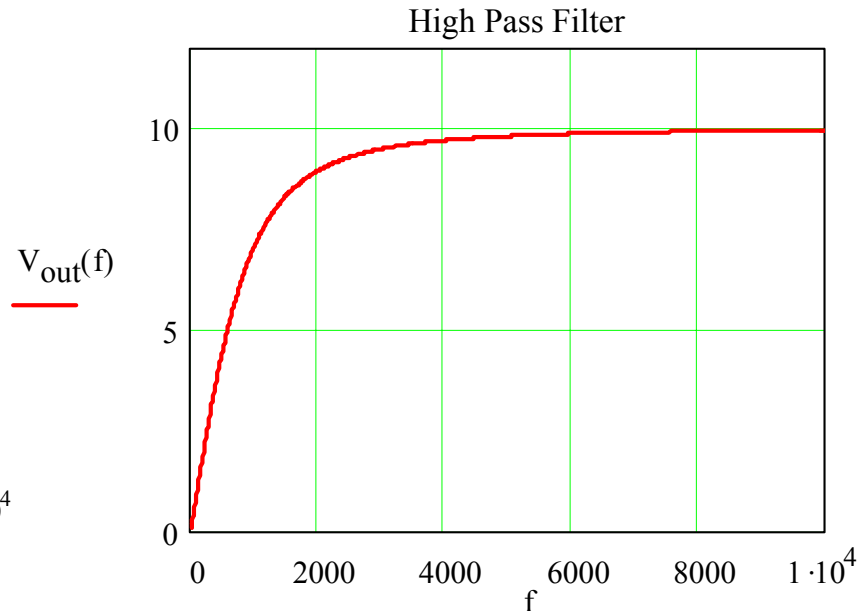
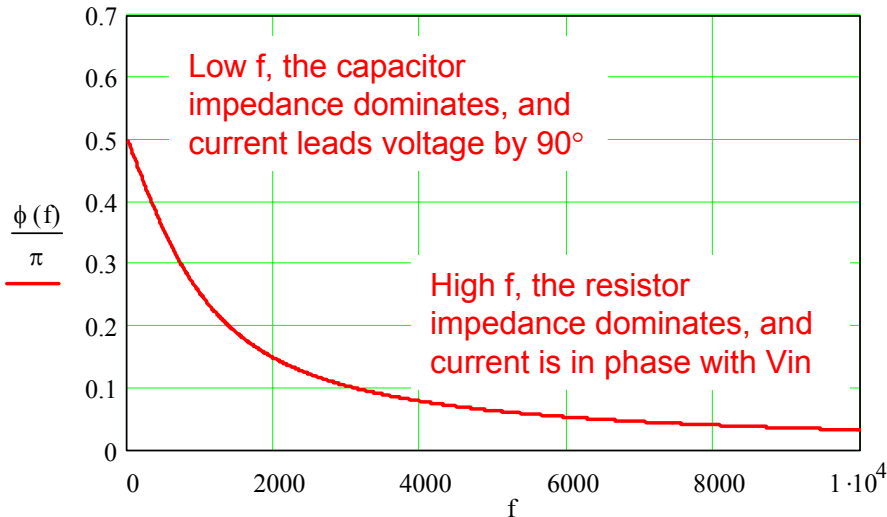
$$V_{out}(f) := V_{in} \cdot \frac{R}{\sqrt{R^2 + \left(\frac{1}{2 \cdot \pi \cdot f \cdot C}\right)^2}}$$

$$V_{out}(100) = 0.994 \quad V_{out}(1000) = 7.068 \quad V_{out}(10000) = 9.95$$

$$V_{out}(300) = 2.871 \quad V_{out}(3000) = 9.486$$

The output (voltage across resistor) is in phase with the current, which leads the input voltage by an angle

$$\phi(f) := \text{atan}\left(\frac{1}{2 \cdot \pi \cdot f \cdot R \cdot C}\right)$$



Problem 35-36  
continued.

This plot demonstrates for one frequency (1500 Hz) how the resistor and capacitor voltages add together at all times to yield the voltage of the source.

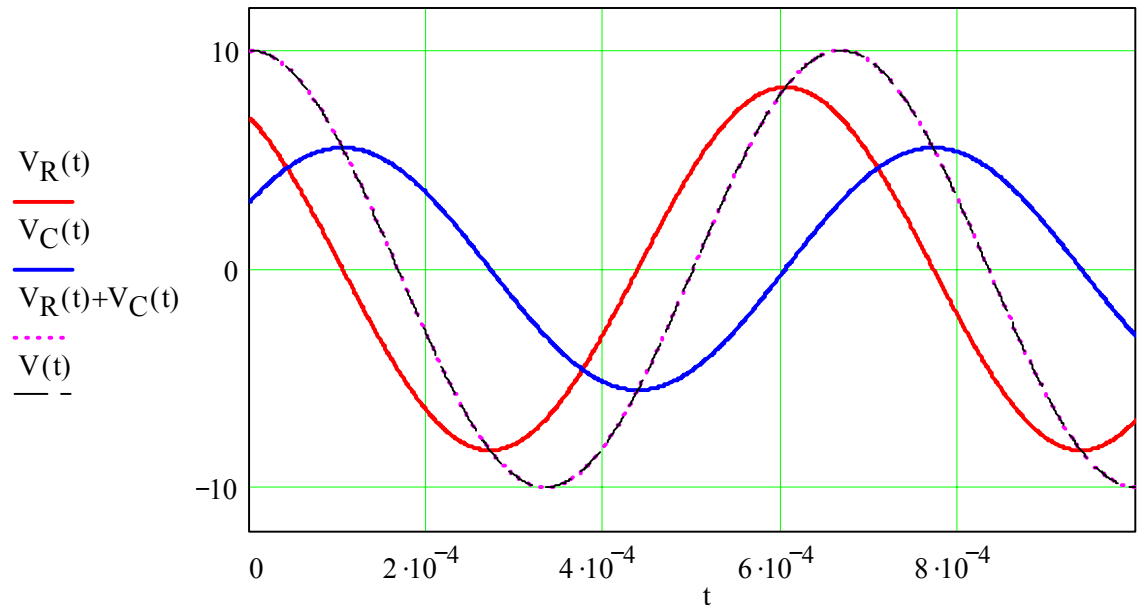
$$\underline{R} := 100 \quad \underline{C} := 1.59 \cdot 10^{-6} \quad V_{\text{in}} := 10 \quad \omega := 2 \cdot \pi \cdot 1500$$

$$\underline{V}(t) := V_{\text{in}} \cdot \cos(\omega \cdot t)$$

$$I_{\text{max}} := \frac{V_{\text{in}}}{\sqrt{R^2 + \left(\frac{1}{\omega \cdot C}\right)^2}} \quad \phi := \text{atan}\left(\frac{1}{\omega \cdot R \cdot C}\right) \quad \phi = 33.716 \text{ deg}$$

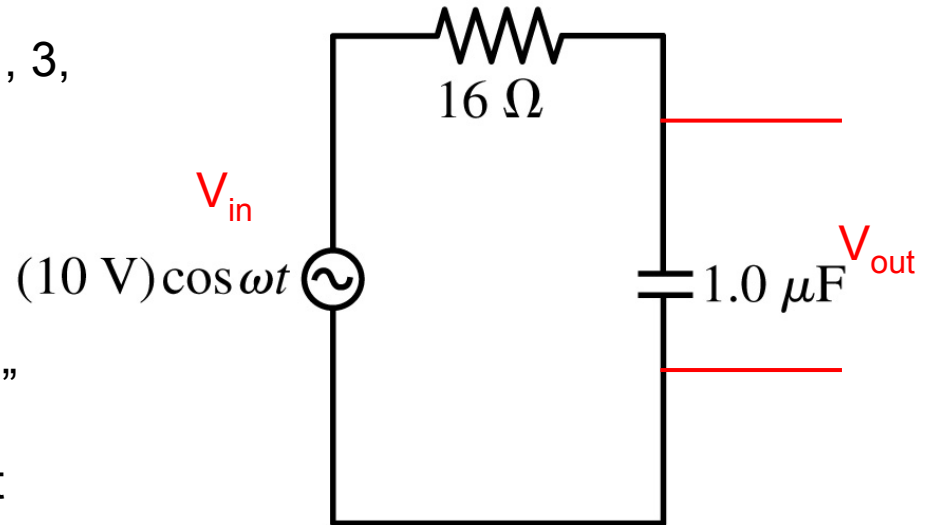
$$I(t) := I_{\text{max}} \cdot \cos(\omega \cdot t + \phi)$$

$$V_R(t) := I_{\text{max}} \cdot R \cdot \cos(\omega \cdot t + \phi) \quad V_C(t) := I_{\text{max}} \cdot \frac{1}{\omega \cdot C} \cdot \cos\left(\omega \cdot t + \phi - \frac{\pi}{2}\right)$$



# Problem 35-37

- Evaluate  $V_C$  at emf frequencies 1, 3, 10, 30, and 100 kilo-Hertz
- Graph  $V_C$  vs frequency.

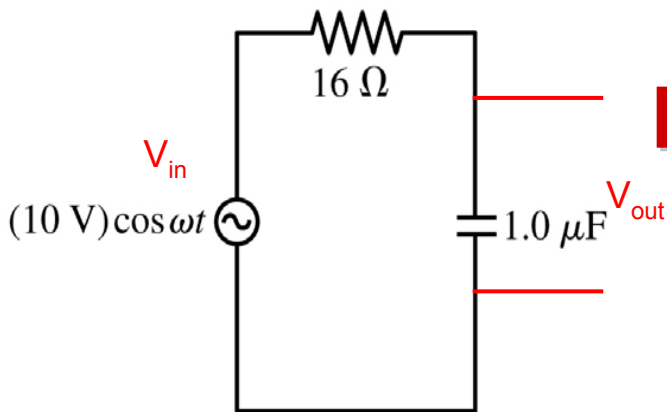


This is an example of a “low pass filter.”

Note that for  $f=0$  (DC) the current must be zero, and therefore  $V_{out}$  is  $V_{in}$ .

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# Problem 35-37

The voltage across the capacitor lags behind the current by  $90^\circ$ , so  $V_{\text{out}}$  has a phase angle

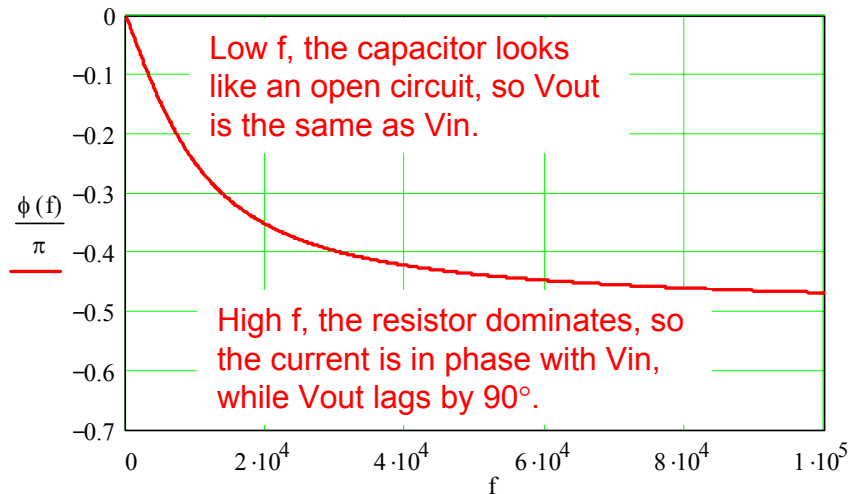
$$R := 16 \quad V_{\text{in}} := 10 \quad C := 1.0 \cdot 10^{-6}$$

$$V_{\text{out}}(f) := V_{\text{in}} \cdot \frac{1}{\sqrt{R^2 + \left(\frac{1}{2 \cdot \pi \cdot f \cdot C}\right)^2}}$$

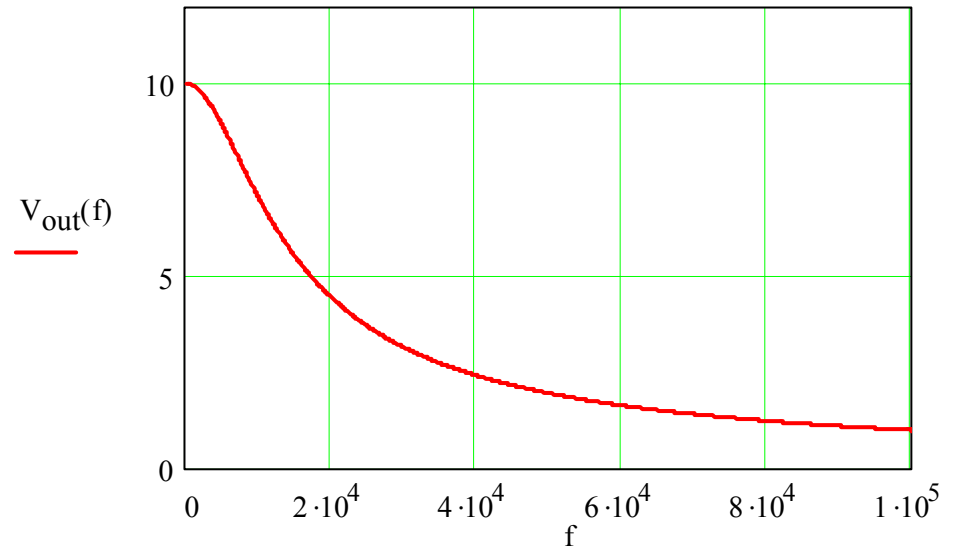
$$V_{\text{out}}(1000) = 9.95 \quad V_{\text{out}}(10000) = 7.052 \quad V_{\text{out}}(100000) = 0.99$$

$$V_{\text{out}}(3000) = 9.574 \quad V_{\text{out}}(30000) = 3.147$$

$$\phi(f) := \text{atan}\left(\frac{1}{2 \cdot \pi \cdot f \cdot R \cdot C}\right) - \frac{\pi}{2}$$

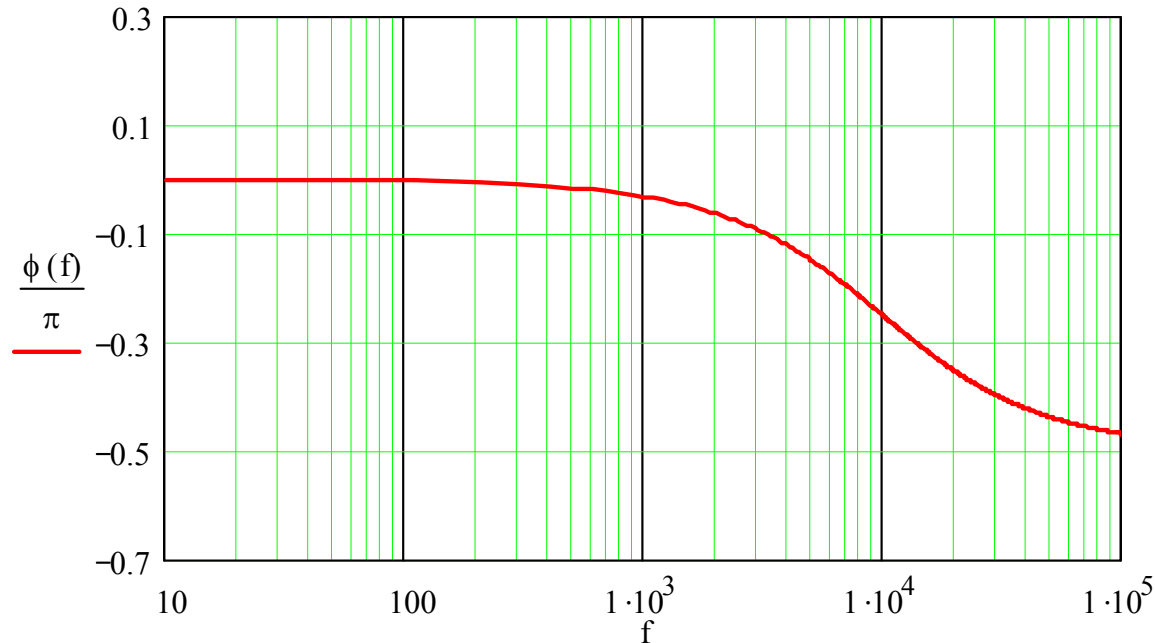


Low Pass Filter



$$\phi(f) := \operatorname{atan}\left(\frac{1}{2 \cdot \pi \cdot f \cdot R \cdot C}\right) - \frac{\pi}{2}$$

## Problem 35-37

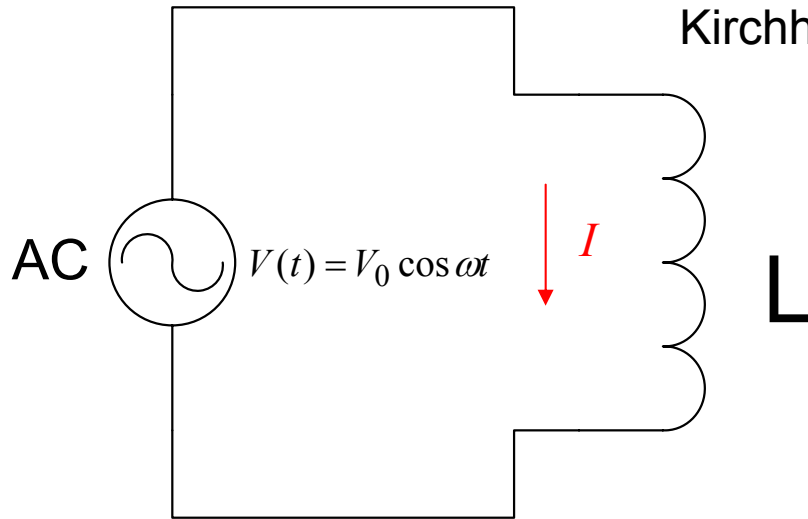


It is very common to plot frequency on a log scale. In that case, the same phase-angle plot looks as shown here.

The point where the phase angle is  $-45^\circ$  is called the cross-over frequency. It occurs where

$$\omega_c = \frac{1}{RC} = 62.5 \text{ kHz or } f = 10 \text{ kHz}$$

# AC Circuits: Inductance



Kirchhoff's rule:  $V(t) + \mathcal{E} = 0$        $\mathcal{E} = -L \frac{dI}{dt}$

$$V = L \frac{dI}{dt}$$

$$I(t) = \frac{1}{L} \int V(t) dt$$

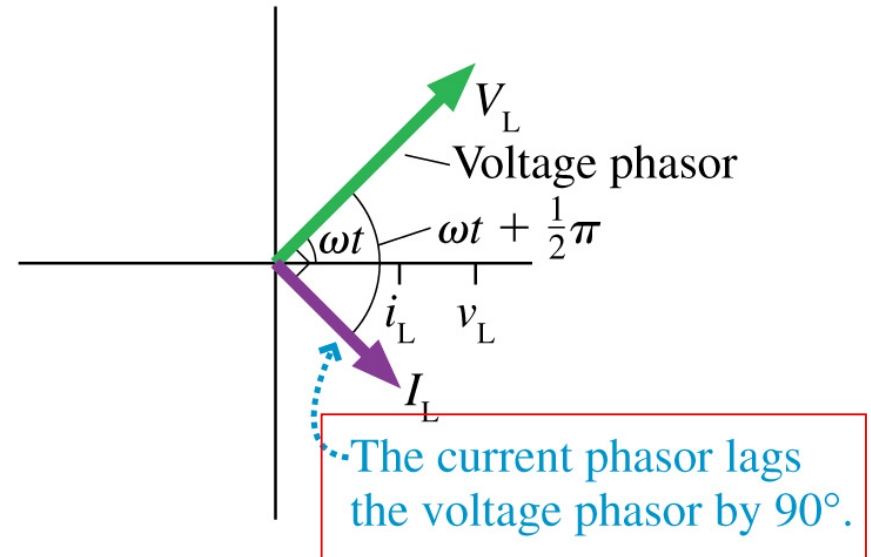
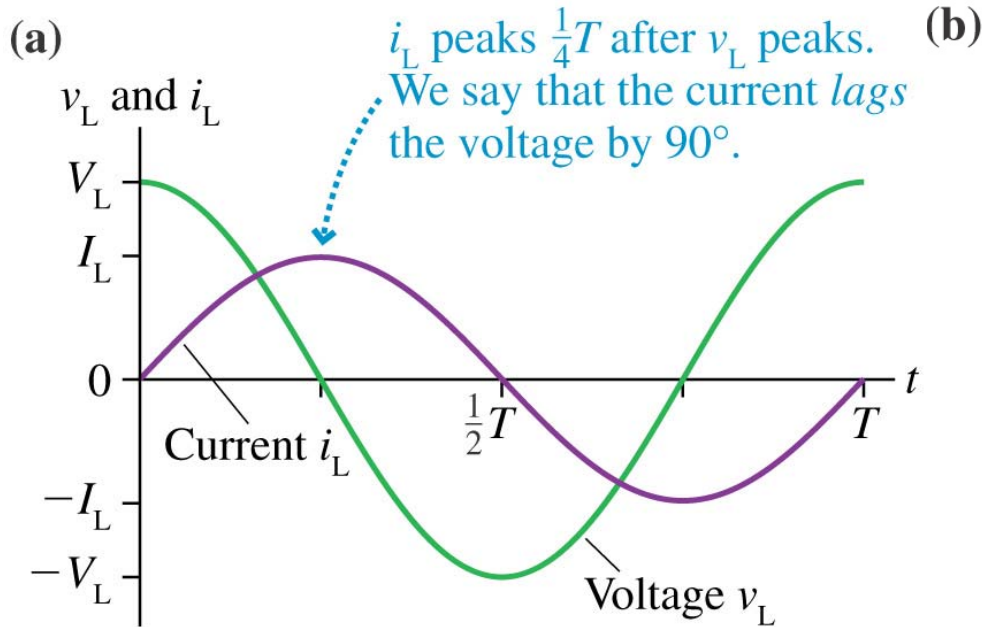
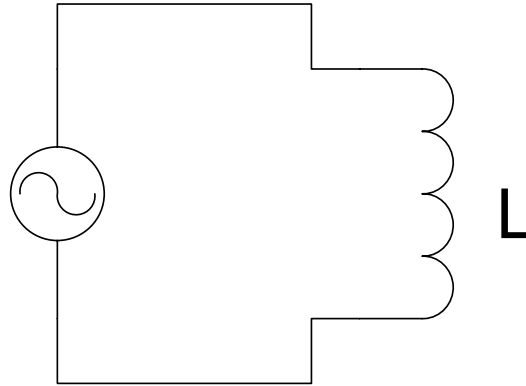
$$I(t) = \frac{V_0}{L} \int \cos \omega t dt$$

$$I(t) = \frac{1}{\omega L} V_0 \sin \omega t$$

$$I(t) = \frac{V_0}{\omega L} \cdot \cos\left(\omega t - \frac{\pi}{2}\right)$$

Energy is stored, NOT dissipated!

# Phasors for Inductive Circuit



# Reactance

All 3 elements provide an “impedance” ( $Z$ ) to the flow of current, but one has to specify a phase difference between current and voltage as well as a change in amplitude.

Assume that the voltage is given by  $V(t) = V_0 \cos \omega t$

$$I(t) = I_{\max} \cos(\omega t + \phi)$$

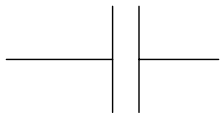
$I$  and  $V$  in phase



$$I(t) = \frac{V_0}{R} \cos \omega t$$

$$Z = R \text{ and } \phi = 0$$

$I$  leads  $V$  by  $90^\circ$

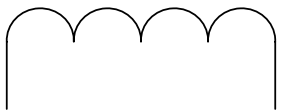


$$I(t) = \frac{V_0}{1/\omega C} \cos(\omega t + \frac{\pi}{2})$$

*Reactance:*

$$Z = X_C = \frac{1}{\omega C} \text{ and } \phi = +\frac{\pi}{2}$$

$I$  lags  $V$  by  $90^\circ$



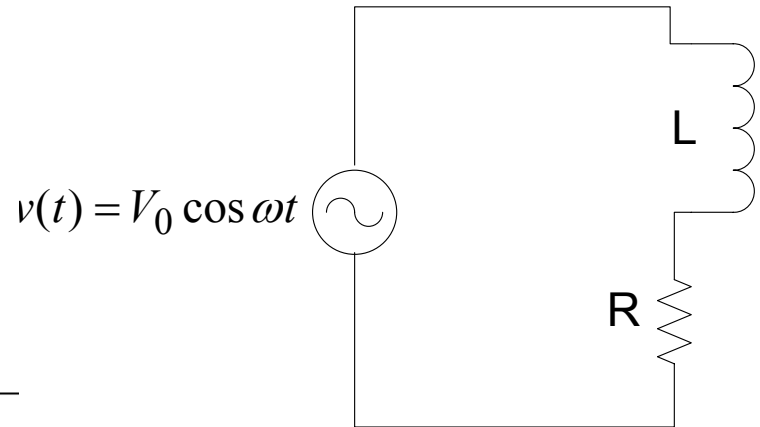
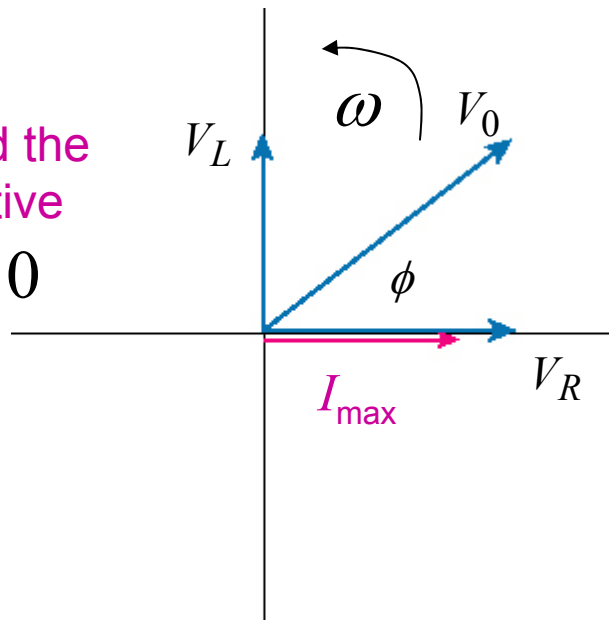
$$I(t) = \frac{V_0}{\omega L} \cos(\omega t - \frac{\pi}{2})$$

$$Z = X_L = \omega L \text{ and } \phi = -\frac{\pi}{2}$$

# RL Circuit with AC Source

- Problem 35-47.

The current is lagging behind the voltage (negative phase).  $\phi < 0$



$$i(t) = I_{\max} \cos(\omega t + \phi)$$

$$V_0 = \sqrt{V_R^2 + V_L^2} = I_{\max} \sqrt{R^2 + (\omega L)^2}$$

$$\phi = -\tan^{-1} \frac{V_L}{V_R} = -\tan^{-1} \frac{\omega L}{R}$$

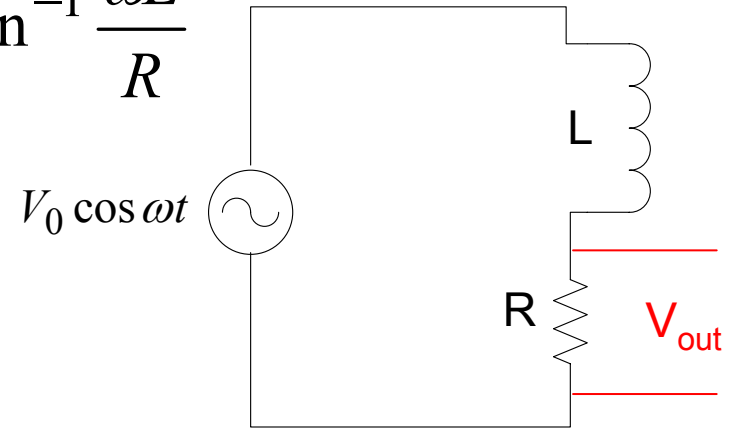
Note:  $Z = \sqrt{R^2 + X_L^2}$

# Problem 35-47, continued

$$i(t) = \frac{V_0}{\sqrt{R^2 + (\omega L)^2}} \cos(\omega t + \phi) \quad \phi = -\tan^{-1} \frac{\omega L}{R}$$

$$v_R(t) = \frac{V_0 \cdot R}{\sqrt{R^2 + (\omega L)^2}} \cos(\omega t + \phi)$$

$$v_L(t) = \frac{V_0 \cdot \omega L}{\sqrt{R^2 + (\omega L)^2}} \cos(\omega t + \phi + \frac{\pi}{2})$$



Part b)  $V_R$  goes to zero as the frequency goes to infinity.

Part c) If  $V_{out} = V_R$ , then this is a low pass filter

Part d) The cross-over frequency occurs when  $R = X_L$ , or equivalently  $V_R = V_L$ . At that point, the output voltage is down by  $1/\sqrt{2}$  and the phase angle is  $-45^\circ$ .

$$\omega_c = \frac{1}{R/L}$$